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Abstract

Successful methods for visual object recognition typically rely on training datasets containing lots of richly annotated images. Detailed image annotation, e.g. by object bounding boxes, however, is both expensive and often subjective. We describe a weakly supervised convolutional neural network (CNN) for object classification that relies only on image-level labels, yet can learn from cluttered scenes containing multiple objects. We quantify its object classification and object location prediction performance on the Pascal VOC 2012 (20 object classes) and the much larger Microsoft COCO (80 object classes) datasets. We find that the network (i) outputs accurate image-level labels, (ii) predicts approximate locations (but not extents) of objects, and (iii) performs comparably to its fully-supervised counterparts using object bounding box annotation for training.

Learning and Transferring Mid-Level Image Representations using Convolutional Neural Networks

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Abstract

Convolutional neural networks (CNN) have recently shown outstanding image classification performance in the large-scale visual recognition challenge (ILSVRC2012). The success of CNNs is attributed to their ability to learn rich mid-level image representations as opposed to hand-designed low-level features used in other image classification methods. Learning CNNs, however, amounts to estimating millions of parameters and requires a very large number of annotated image samples. This property currently prevents application of CNNs to problems with limited training data.

In this work we show how image representations learned with CNNs on large-scale
annotated datasets can be efficiently transferred to other visual recognition tasks with limited amount of training data. We design a method to reuse layers trained on the ImageNet dataset to compute mid-level image representation for images in the PASCAL VOC dataset. We show that despite differences in image statistics and tasks in the two datasets, the transferred representation leads to significantly improved results for object and action classification, outperforming the current state of the art on Pascal VOC 2007 and 2012 datasets. We also show promising results for object and action localization.